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ADDISON SMITH

*Mechanical Contractor, Inc.*

HPPG 89ki EXPANSION PROJECT

VFD Submittal Data

Spec 15855



Power and productivity  
for a better world™

## **Project Submittal for Honda 89KI Expansion**

**Specification: 15855**

**Engineering Contact: SSOE**

**Contractor: Addison Smith**

**Architect:**

**End Customer (User): Honda**

**Submitted By: BJ Borie, Borie-Davis Inc**

**Revision: A**

**Date: 01/06/14**

# Submittal Schedule

This schedule includes the products supplied as part of this submittal.

Schedule			Motor Data <sup>1</sup>			Drive Data			
Tagging /						Output			
Item	Qty	Equipment ID	HP	FLA	Voltage	Product ID	HP	Amps	Voltage
1	2	CHWP-11,12	125	156	460 VAC	ACH550-BCR-157A-4+B055	125	157	480 VAC
2	2	CWP-13,14	100	124	460 VAC	ACH550-BCR-125A-4+B055	100	124	480 VAC
3	2	ICWP-17,18	20	27	460 VAC	ACH550-BCR-031A-4+B055	20	31	480 VAC
4	4	PWP-3,4, CT-4,5	60	77	460 VAC	ACH550-BCR-078A-4+B055	60	77	480 VAC

**Notes:** 1. AC Motor Data is per National Electrical Code Table 430.250 for typical motors used in most applications and is provided as typical data only. DC motor data is per typical industry standards. Actual motor data may vary.

## Submittal Schedule Details for CHWP-11,12

Item	Tag / Equipment ID	Product ID
1	CHWP-11,12	ACH550-BCR-157A-4+B055

Item Description
<b>Input Voltage:</b> 480 VAC <b>Rated Output Current:</b> 157 AMPS <b>Construction:</b> E-clipse-Bypass, Circuit Breaker <b>Enclosure:</b> NEMA/UL Type 12 <b>Nominal Horsepower:</b> 125 <b>Frame Size:</b> R6 <b>Input Disconnecting Means:</b> Circuit Breaker <b>Bypass:</b> E-Clipse Bypass <b>Input Impedance:</b> 5% <b>Short Circuit Current Rating:</b> 100 kA <b>Communication Protocols:</b> Johnson Controls N2, Siemens Buildings Technologies FLN (P1), Modbus RTU, BACnet <b>Other Options:</b> <b>Recommended Spare Parts Package :</b>

Drive Input Fuse Ratings	
(Note: Drive is UL approved without the need for input fuses. Fuse rating information provided for customer reference)	
Amps (600 V)	Bussmann Type
200	170M1370 or M2617

Wire Size Capacities of Power Terminals				
Circuit Breaker	Disconnect Switch	Terminal Block	Overload Relay	Ground Lug
350MCM 274 in-lbs	N/A N/A	250 MCM 300 in-lbs	N/A N/A	3 x #3/0 250 in-lbs

Dimensions and Weights				
Height in / mm	Width in / mm	Depth in / mm	Weight lbs / kg	Dimension Drawing
54.3 / 1380	28.1 / 713	19 / 483	360 / 163	3AUA0000016382 Sheet 1

Heat Dissipation & Airflow Requirements			
Power Losses		Airflow	
Watts	BTU/Hr	CFM	CM/Hr
2310	7884	238	405

Reference Drawings		
Power Wiring	Connection Diagram	Dimension Detail
BC00R046PW-A	BCBDR016CC-A	3AUA0000016382 Sheet 1

## Submittal Schedule Details for CWP-13,14

Item	Tag / Equipment ID	Product ID
2	CWP-13,14	ACH550-BCR-125A-4+B055

Item Description
<b>Input Voltage:</b> 480 VAC <b>Rated Output Current:</b> 124 AMPS <b>Construction:</b> E-clipse-Bypass, Circuit Breaker <b>Enclosure:</b> NEMA/UL Type 12 <b>Nominal Horsepower:</b> 100 <b>Frame Size:</b> R5 <b>Input Disconnecting Means:</b> Circuit Breaker <b>Bypass:</b> E-clipse Bypass <b>Input Impedance:</b> 5% <b>Short Circuit Current Rating:</b> 100 kA <b>Communication Protocols:</b> Johnson Controls N2, Siemens Buildings Technologies FLN (P1), Modbus RTU, BACnet <b>Other Options:</b> <b>Recommended Spare Parts Package :</b>

Drive Input Fuse Ratings	
(Note: Drive is UL approved without the need for input fuses. Fuse rating information provided for customer reference)	
Amps (600 V)	Bussmann Type
200	170M1370 or M2617

Wire Size Capacities of Power Terminals				
Circuit Breaker	Disconnect Switch	Terminal Block	Overload Relay	Ground Lug
350MCM 274 in-lbs	N/A N/A	250 MCM 300 in-lbs	N/A N/A	3 x #3/0 250 in-lbs

Dimensions and Weights				
Height in / mm	Width in / mm	Depth in / mm	Weight lbs / kg	Dimension Drawing
54.3 / 1380	28.1 / 713	19 / 483	266 / 121	3AUA0000016382 Sheet 1

Heat Dissipation & Airflow Requirements			
Power Losses		Airflow	
Watts	BTU/Hr	CFM	CM/Hr
1940	6621	99	168

Reference Drawings		
Power Wiring	Connection Diagram	Dimension Detail
BC00R046PW-A	BCBDR016CC-A	3AUA0000016382 Sheet 1

## Submittal Schedule Details for ICWP-17,18

Item	Tag / Equipment ID	Product ID
3	ICWP-17,18	ACH550-BCR-031A-4+B055

Item Description
<b>Input Voltage:</b> 480 VAC <b>Rated Output Current:</b> 31 AMPS <b>Construction:</b> E-clipse-Bypass, Circuit Breaker <b>Enclosure:</b> NEMA/UL Type 12 <b>Nominal Horsepower:</b> 20 <b>Frame Size:</b> R3 <b>Input Disconnecting Means:</b> Circuit Breaker <b>Bypass:</b> E-clipse Bypass <b>Input Impedance:</b> 5% <b>Short Circuit Current Rating:</b> 100 kA <b>Communication Protocols:</b> Johnson Controls N2, Siemens Buildings Technologies FLN (P1), Modbus RTU, BACnet <b>Other Options:</b> <b>Recommended Spare Parts Package :</b>

Drive Input Fuse Ratings	
(Note: Drive is UL approved without the need for input fuses. Fuse rating information provided for customer reference)	
Amps (600 V)	Bussmann Type
60	JJS-60

Wire Size Capacities of Power Terminals				
Circuit Breaker	Disconnect Switch	Terminal Block	Overload Relay	Ground Lug
#1 50 in-lbs	N/A N/A	#2 50 in-lbs	N/A N/A	#2 50 in-lbs

Dimensions and Weights				
Height in / mm	Width in / mm	Depth in / mm	Weight lbs / kg	Dimension Drawing
37.4 / 950	20.5 / 521	15.3 / 389	120 / 54.4	3AUA0000016379 Sheet 1

Heat Dissipation & Airflow Requirements			
Power Losses		Airflow	
Watts	BTU/Hr	CFM	CM/Hr
457	1560	79	134

Reference Drawings		
Power Wiring	Connection Diagram	Dimension Detail
BC00R024PW-A	BCBDR016CC-A	3AUA0000016379 Sheet 1

## Submittal Schedule Details for PWP-3,4, CT-4,5

Item	Tag / Equipment ID	Product ID
4	PWP-3,4, CT-4,5	ACH550-BCR-078A-4+B055

Item Description
<b>Input Voltage:</b> 480 VAC <b>Rated Output Current:</b> 77 AMPS <b>Construction:</b> E-clipse-Bypass, Circuit Breaker <b>Enclosure:</b> NEMA/UL Type 12 <b>Nominal Horsepower:</b> 60 <b>Frame Size:</b> R4 <b>Input Disconnecting Means:</b> Circuit Breaker <b>Bypass:</b> E-Clipse Bypass <b>Input Impedance:</b> 5% <b>Short Circuit Current Rating:</b> 100 kA <b>Communication Protocols:</b> Johnson Controls N2, Siemens Buildings Technologies FLN (P1), Modbus RTU, BACnet <b>Other Options:</b> <b>Recommended Spare Parts Package :</b>

Drive Input Fuse Ratings	
(Note: Drive is UL approved without the need for input fuses. Fuse rating information provided for customer reference)	
Amps (600 V)	Bussmann Type
100	JJS-100

Wire Size Capacities of Power Terminals				
Circuit Breaker	Disconnect Switch	Terminal Block	Overload Relay	Ground Lug
#1 50 in-lbs	N/A N/A	#2/0 120 in-lbs	N/A N/A	#2 50 in-lbs

Dimensions and Weights				
Height in / mm	Width in / mm	Depth in / mm	Weight lbs / kg	Dimension Drawing
37.4 / 950	20.5 / 521	15.3 / 389	138 / 62.6	3AUA0000016379 Sheet 1

Heat Dissipation & Airflow Requirements			
Power Losses		Airflow	
Watts	BTU/Hr	CFM	CM/Hr
1295	4420	165	280

Reference Drawings		
Power Wiring	Connection Diagram	Dimension Detail
BC00R024PW-A	BCBDR016CC-A	3AUA0000016379 Sheet 1

# ACH550 Product Overview

## ***Description***

The ACH550 series is a microprocessor based Pulse Width Modulated (PWM) adjustable speed AC drive. The ACH550 drive takes advantage of sophisticated microprocessor control and advanced IGBT power switching technology to deliver high-performance control of AC motors for a wide range of HVAC applications.

With drives ranging from 1 to 550 HP, the ACH550 series features a universal full graphic interface that “speaks” to the operator in plain English phrases, greatly simplifying set-up, operation, and fault diagnosis. The ACH550 is also programmable in fourteen other languages.

Each ACH550 drive comes equipped with an extensive library of pre-programmed HVAC application macros which, at a touch of a button, allow rapid configuration of inputs, outputs, and performance parameters for specific HVAC applications to maximize convenience and minimize start-up time. The ACH550 series can handle the most demanding commercial applications in an efficient, dependable, and economic manner.



## ACH550 Standard Features

UL, cUL labeled and CE marked, BTL listed  
EMI/RFI Filter (1<sup>st</sup> Environment, Restricted Distribution)  
Seismic Certificate of Compliance in accordance with  
IBC 2000 referencing ASCE 7-98 and ICC AC156  
IBC 2003 referencing ASCE 7-02 and ICC AC156  
IBC 2006 referencing ASCE 7-05 and ICC AC156  
IBC 2009 referencing ASCE 7-05 and ICC AC156  
Start-Up Assistants  
Maintenance Assistants  
Diagnostic Assistants  
Real Time Clock  
Includes Day, Date and Time  
Operator Panel Parameter Backup (read/write)  
Full Graphic and Multilingual Display  
for Operator Control, Parameter Set-Up and Operating  
Data Display:  
Output Frequency (Hz) / Motor Speed (RPM)  
Motor Current  
Calculated Energy Savings (\$, kWh/MWh, CO<sup>2</sup>)  
Calculated % Motor Torque  
Calculated Motor Power (kW)  
DC Bus Voltage  
Output Voltage  
Heatsink Temperature  
Elapsed Time Meter (reset-able)  
KWh (reset-able)  
Input / Output Terminal Monitor  
PID Actual Value (Feedback) & Error  
Fault Text  
Warning Text  
Three (3) Scalable Process Variable Displays  
User Definable Engineering Units  
Two (2) Programmable Analog Inputs  
Six (6) Programmable Digital Inputs  
Two (2) Programmable Analog Outputs  
Up to six (6) Programmable Relay Outputs (Three (3) Standard)  
Adjustable Filters on Analog Inputs and Outputs  
Mathematical Functions on Analog Reference Signals  
All Control Inputs Isolated from Ground and Power  
Four (4) Resident Serial Communication Protocols  
BACnet (MS/TP)  
Johnson Controls N2  
Siemens Building Technologies FLN (P1)  
Modbus RTU  
Input Speed Signals  
Current 0 (4) to 20 mA  
Voltage 0 (2) to 10 VDC  
Increase/Decrease Reference Contacts (Floating Point)  
Serial Communications  
Start/Stop  
2 Wire (Dry Contact Closure)  
3 Wire (Momentary Contact)  
Application of Input Power  
Application of Reference Signal (PID Sleep/Wake-Up)  
Serial Communications  
Start Functions  
Ramp  
Flying Start  
Pre-magnetization (DC Brake) on Start  
Automatic Torque Boost  
Automatic Torque Boost with Flying Start  
Auto Restart (Reset) – Customer Selectable and Adjustable  
Stop Functions  
Ramp or Coast to Stop  
Emergency Stop  
DC Braking / Hold at Stop  
Flux Braking  
Accel/Decel  
Two (2) sets of Independently Ramps  
Linear or Adjustable 'S' Curve Accel/Decel Ramps

HVAC Specific Application Macros  
Separate Safeties (2) and Run Permissive Inputs  
Damper Control  
Override Input (Fire Mode)  
Timer Functions  
Four (4) Daily Start/Stop Time Periods  
Four (4) Weekly Start/Stop Time Periods  
Four Timers for Collecting Time Periods and Overrides  
Seven (7) Preset Speeds  
Supervision Functions  
Adjustable Current Limit  
Electronic Reverse  
Automatic Extended Power Loss Ride Through (Selectable)  
Programmable Maximum Frequency to 500 Hz  
PID Control  
Two (2) Integral Independent Programmable PID Setpoint Controllers (Process and External)  
External Selection between Two (2) Sets of Process PID Controller Parameters  
PID Sleep/Wake-Up  
Motor Control Features  
Scalar (V/Hz) and Vector Modes of Motor Control  
V/Hz Shapes  
Linear  
Squared  
Energy Optimization  
IR Compensation  
Slip Compensation  
Three (3) Critical Frequency Lockout Bands  
Preprogrammed Protection Circuits  
Overcurrent  
Short Circuit  
Ground Fault  
Overvoltage  
Undervoltage  
Input Phase Loss  
Output Device (IGBT) Overtemperature  
Adjustable Current Limit Regulator  
UL508C approved Electronic Motor Overload (I<sup>2</sup>T)  
Programmable Fault Functions for Protection Include  
Loss of Analog Input  
Panel Loss  
External Fault  
Motor Thermal Protection  
Stall  
Underload  
Motor Phase Loss  
Ground Fault  
Input Impedance  
5% Equivalent Impedance with Internal Reactor(s)  
Patented Swinging Choke Design for Superior Harmonic Mitigation (R1...R6 Frames)  
3% Equivalent Impedance (R8 Frame)

### OPTIONAL FEATURES

3 Relay Extension Module (OREL-01)  
115/230 V Digital input Interface Card (OHDI-01)  
Fieldbus Adapter Modules  
LonWorks  
BACnet IP to MS/TP Router  
Profibus  
DeviceNet  
Ethernet  
ControlNet  
DriveWindow Light Start-up, Operation, Programming and Diagnostic Tool  
Fan Replacement Kit

# ACH550 Specifications

## Input Connection

Input Voltage (U <sub>1</sub> )	208/220/230/240 VAC 3-phase +/-10%
	208/220/230/240 VAC 1-phase +/-10%
	380/400/415/440/460/480 VAC 3-phase +/-10%
Frequency	48 - 63 Hz
Line Limitations	Max +/-3% of nominal phase to phase input voltage
Fundamental Power Factor (cosφ)	0.98 at nominal load
Connection	U <sub>1</sub> , V <sub>1</sub> , W <sub>1</sub> (U <sub>1</sub> , V <sub>1</sub> , 1-phase)

## Output (Motor) Connection

Output Voltage	0 to U <sub>1</sub> , 3-phase symmetrical, U <sub>2</sub> at the field weakening point
Output Frequency	-500 to 500 Hz
Frequency Resolution	0.01 Hz
Continuous Output Current	
Variable Torque	1.0 * I <sub>2N</sub> (Nominal rated output current, Variable Torque)
Short Term Overload Capacity	
Variable Torque	1.1 * I <sub>2N</sub> , (1 min/10 min)
Peak Overload Capacity	
Variable Torque	1.35 * I <sub>2N</sub> , (2 sec/1 min)
Base Motor Frequency Range	10 to 500 Hz
Switching Frequency	1, 4, 8 or 12 kHz
Acceleration Time	0.1 to 1800 s
Deceleration Time	0.1 to 1800 s
Efficiency	0.98 at nominal power level
Short Circuit Withstand Rating	100,000 AIC (UL) w/o fuses
Connection	U <sub>2</sub> , V <sub>2</sub> , W <sub>2</sub>

## Enclosure

Style: UL (NEMA) Type 1, Type 12, or Type 3R

## Agency Approval

Listing and Compliance: UL, cUL, CE

## Ambient Conditions, Operation

Air Temperature	-15 <sup>0</sup> to 40 <sup>0</sup> C (5 <sup>0</sup> to 104 <sup>0</sup> F), above 40 <sup>0</sup> C the maximum output current is de-rated 1% for every additional 1 <sup>0</sup> C (up to 50 <sup>0</sup> C (122 <sup>0</sup> F) maximum limit.
Relative Humidity	5 to 95%, no condensation allowed, maximum relative humidity is 60% in the presence of corrosive gasses
Contamination Levels	
IEC	60721-3-1, 60721-3-2 and 60721-3-3
Chemical Gasses	3C1 and 3C2
Solid Particles	3S2
Installation Site Altitude	0 to 1000 m (3300 ft) above sea level. At sites over 1000 m (3300 ft) above sea level, the maximum power is de-rated 1% for every additional 100 m (330 ft). If the installation site is higher than 2000 m (6600 ft) above sea level, please contact your local ABB distributor or representative for further information
Vibration	Max 3.0 mm (0.12 in) 2 to 9 Hz, Max 10 m/s <sup>2</sup> (33 ft/s <sup>2</sup> ) 9 to 200 Hz sinusoidal Seismic Certified referencing IBC 2000, 2003, 2006 and 2009

## Ambient Conditions, Storage (in Protective Shipping Package)

Air Temperature	-40 <sup>0</sup> to 70 <sup>0</sup> C (-40 <sup>0</sup> to 158 <sup>0</sup> F)
Relative Humidity	Less than 95%, no condensation allowed
Vibration	In accordance with ISTA 1A and 1B specifications
Shock (IEC 60086-2-29)	Max 100 m/s <sup>2</sup> (330 ft/s <sup>2</sup> ) 11 ms

## Ambient Conditions, Transportation (in Protective Shipping Package)

Air Temperature	-40 <sup>0</sup> to 70 <sup>0</sup> C (-40 <sup>0</sup> to 158 <sup>0</sup> F)
Relative Humidity	Less than 95%, no condensation allowed
Atmospheric Pressure	60 to 106 kPa (8.7 to 15.4 PSI)
Vibration	Max 3.5 mm (0.14 in) 2 to 9 Hz, Max 15 m/s <sup>2</sup> (49 ft/s <sup>2</sup> ) 9 to 200 Hz sinusoidal
Shock (IEC 60086-2-29)	Max 100 m/s <sup>2</sup> (330 ft/s <sup>2</sup> ) 11 ms
Free Fall	R1: 76 cm (30 in) R2: 61 cm (24 in) R3: 46 cm (18 in) R4: 31 cm (12 in) R5 & 6: 25 cm (10 in)

## Cooling Information

Cooling Method	Integral fan(s)
Power Loss	Approximately 3% of rated power

## ACH550 Specifications (continued)

### Analog Inputs

Quantity	Two (2) programmable
Voltage Reference:	0 (2) to 10 V, 312kOhm, single ended
Current Reference:	0 (4) to 20 mA, 100Ohm, single ended
Potentiometer:	10 VDC, 10 mA (1K to 10KOhms)
Input Updating Time	8 ms
Terminal Block Size	2.3mm <sup>2</sup> / 14AWG

### Reference Power Supply

Reference Voltage	+10 VDC, 1% at 25°C (77°F)
Maximum Load	10 mA
Applicable Potentiometer	1 kOhm to 10 kOhm
Terminal Block Size	2.3mm <sup>2</sup> / 14AWG

### Analog Outputs

Quantity	Two (2) programmable current outputs
Signal Level	0 (4) to 20 mA
Accuracy	+/- 1% full scale range at 25°C (77°F)
Maximum Load Impedance	500 Ohms
Output Updating Time	2 ms
Terminal Block Size	2.3mm <sup>2</sup> / 14AWG

### Digital Inputs

Quantity	Six (6) programmable digital inputs
Isolation	Isolated as one group
Signal Level	24 VDC, (10V Logic 0)
Input Current	15 mA at 24 VDC
Input Updating Time:	4 ms
Terminal Block Size	2.3mm <sup>2</sup> / 14AWG

### Internal Power Supply

Primary Use	Internal supply for digital inputs
Voltage:	+24 VDC, max 250 mA
Maximum Current:	250 mA
Protection:	Short circuit protected

### Relay Outputs

Quantity	Three (3) programmable relay (Form C) outputs
Switching Capacity:	8 A at 24 VDC or 250 VAC, 0.4 A at 120 VDC
Max Continuous Current:	2A RMS
Contact Material:	Silver Cadmium Oxide (AgCdO)
Isolation Test Voltage	4 kVAC, 1 minute
Output Updating Time	12 ms
Terminal Block Size	2.3mm <sup>2</sup> / 14AWG

### Protections

Single Phase	Protected (input & output)
Overcurrent Trip Limit:	3.5 x I <sub>2N</sub> instantaneous
Adjustable Current Regulation Limit:	1.1 x I <sub>2N</sub> (RMS) max.
Overvoltage Trip Limit:	1.30 x U <sub>N</sub>
Undervoltage Trip Limit:	0.65 x U <sub>N</sub>
Overtemperature (Heatsink):	+115°C (+239°F)
Auxiliary Voltage:	Short Circuit Protected
Ground Fault:	Protected
Short Circuit:	Protected
Microprocessor fault:	Protected
Motor Stall Protection:	Protected
Motor Overtemperature Protection (I <sub>2t</sub> ):	Protected
Input Power Loss of Phase:	Protected
Loss of Reference:	Protected
Short Circuit Current Rating:	100,000 RMS symmetrical Amperes
Input Line Impedance:	Swinging choke 5% equivalent R1-R6, 3% equivalent R8

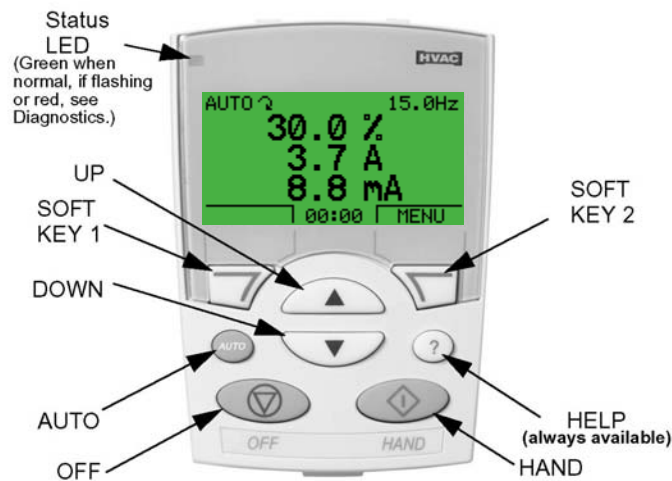
U<sub>1</sub> = Input Voltage  
U<sub>2</sub> = Output Voltage  
P<sub>N</sub> = Power – Normal Duty (HP)

U<sub>N</sub> = Nominal Motor Voltage  
f<sub>N</sub> = Nominal Motor Frequency  
I<sub>2N</sub> = Nominal Motor Current – Normal Duty

Specifications are subject to change without notice. Please consult the factory when specifications are critical.

## ACH550 Control Panel

The ACH550 Control Panel is a multifunction control panel with full graphic LCD display and multiple language capability. The control panel can be connected to and detached from the ACH550 at any time. The panel can be used to upload and copy parameters to other ACH550 drives.



**Run Indication and Shaft Direction** ↻ located in upper left corner of display.

Control Panel Display	Significance
Rotating arrow (clockwise or counterclockwise)	Drive is running and at set point Shaft direction is forward or reverse
Rotating arrow blinking	Drive is operating but not at setpoint
Stationary arrow	Drive is stopped

### LED Indicators

The green LED indicates that the power is on and the drive is operating normally. The red LED indicates a fault. A blinking green LED indicates an alarm condition. A blinking red LED indicates a fault that requires power to be cycled off and on to reset the drive.

### Fault Indications

The ACH550 Control Panel can display over 20 alarm and fault messages. The last fault and previous faults (1 to 9) are retained in memory. The last fault and previous faults (1 & 2) also record important diagnostic information to assist in troubleshooting. Most faults can be reset by pressing the RESET key (Soft Key 1).

### Parameters

Application specific parameters are immediately accessible through a selection of start-up “Assistants”. A complete list of parameters is also available grouped by function in approximately 33 menu groups. One of the basic menu functions can be used to display the complete list of changed parameters.

### Real Time Clock

The Operator Control Panel includes a real time clock which provides Day, Date and Time information, displayed in a choice of formats. The real time clock has a 10 year battery back up and provides time and date stamping of drive faults and other events. The clock is also used by the ACH550s internal timer functions, providing an integral time clock for start/stop control as well as other control operations.

## Control Modes

When the HAND key is pressed, the drive starts and pressing the UP/DOWN keys can modify the reference frequency. The HAND (keypad) control mode is indicated.

When the OFF key is pressed, the drive stops and the OFF control mode is indicated.

When the AUTO key is pressed, the AUTO control mode is indicated. The drive can be started and stopped using whichever remote start/stop command has been configured, a contact closure applied to the start/stop input, a serial communication command or a process feedback signal. In AUTO mode the drive speed is typically controlled by the external speed reference input or by the PID controller.

If the HAND key is pressed while the drive is running in the AUTO control mode, the drive continues to run without changing speed, but ceases to respond to external input or PID speed reference changes. (Bumpless transfer) Pressing the UP/DOWN keys can modify the reference frequency.

If the AUTO key is pressed while the drive is running in the HAND control mode and an external start command is present, the drive continues to run and follows the acceleration or deceleration control ramp to the speed set by the external input or PID speed reference. (Bumpless transfer)

## Cable Connections

Terminal	Description	Note
U1, V1, W1	3~ power supply input	Use of 1~ supply requires 50% derate of output current and is applicable for 208 to 240 VAC operation only.
PE / GND	Protective Ground	Follow local rules for cable size.
U2, V2, W2	Power output to motor	
Uc+, Uc-	DC bus	
X1 1 to 18	Control Wiring	Low voltage control – Use shielded cable
X1 19 to 27	Control Wiring	Low voltage or 115VAC
X1 28 to 32	Serial Communications	Use shielded cable

Follow local codes for cable size. To avoid electromagnetic interference, use separate metallic conduits for input power wiring, motor wiring, control and communications wiring. Keep these four classes of wiring separated in situations where the wiring is not enclosed in metallic conduit. Also, keep 115VAC control wiring separated from low voltage control wiring and power wiring.

Use shielded cable for control wiring.

Ampacity is based on the use of 60 °C rated power cable up to 100 Amps (75 °C over 100 Amps).

Refer to the included tables for current ratings, fuse recommendations and maximum wire size capacities and tightening torques for the terminals. The ACH550 is suitable for use on a circuit capable of delivering not more than 100,000 RMS symmetrical amperes, 480 V maximum. The ACH550 has an electronic motor protection feature that complies with the requirements of the National Electric Code (NEC). When this feature is selected and properly adjusted. Additional overload protection is not required unless more than one motor is connected to the drive or unless additional protection is required by applicable safety regulations.

For CE installation requirements, see ABB publication CE-US-02 “CE Council Directives and Variable Speed Drives.” Contact your local ABB representative for specific IEC installation instructions.

## ACH550 Control Terminals - Main I/O Terminal X1

X1	Identification	Description
1	SCR	Terminal for signal cable screen. (Connected internally to chassis ground.)
2	AI 1	Analog input channel 1, programmable. Default <sup>2</sup> = External reference Resolution 0.1 % accuracy $\pm 1$ %. 0 (4) - 20 mA ( $R_i = 312 \text{ k}\Omega$ ) (J1:AI1 ON) 0 (2) - 10 V ( $R_i = 100 \Omega$ ) (J1:AI1 OFF)
3	AGND	Analog input common. (Connected internally to chassis ground through 1 M $\Omega$ )
4	10 V	10 V/10 mA reference voltage output for analog input potentiometer, accuracy $\pm 2$ %. (1 k $\Omega \leq R \leq 10 \text{ k}\Omega$ )
5	AI 2	Analog input channel 2, programmable. Default <sup>2</sup> = PID Feedback Resolution 0.1 % accuracy $\pm 1$ %. 0 (4) - 20 mA ( $R_i = 312 \text{ k}\Omega$ ) (J1:AI2 ON) 0 (2) - 10 V ( $R_i = 100 \Omega$ ) (J1:AI2 OFF)
6	AGND	Analog input common. (Connected internally to chassis ground through 1 M $\Omega$ )
7	AO1	Analog output channel 1, programmable. Default <sup>2</sup> = Output frequency 0 (4) - 20 mA (load < 500 $\Omega$ ), accuracy $\pm 3$ % full scale.
8	AO2	Analog output channel 2, programmable. Default <sup>2</sup> = Output current 0 (4) - 20 mA (load < 500 $\Omega$ ), accuracy $\pm 3$ % full scale.
9	AGND	Analog output common. Connected internally to chassis ground through 1 M $\Omega$ )
10	24 V	Auxiliary voltage output 24 V DC / 250 mA (Reference to AGND). Short circuit protected.
11	GND	Common for digital input (DI) return signals.
12	DCOM	Digital input circuit common for all digital inputs (DIs). Connected internally as floating.
DI Configuration <sup>1</sup>		To activate a digital input, there must be $\geq +10$ V (or $\leq -10$ V) between that input and DCOM. The 24 V may be provided by the ACH550 (X1:10) or by an external 12-24 V source of either polarity.
13	DI 1	Digital input 1, programmable. Default <sup>2</sup> = Start/Stop (AUTO mode) Activation starts the drive
14	DI 2	Digital input 2, programmable. Default <sup>2</sup> = Not configured.
15	DI 3	Digital input 3, programmable. Default <sup>2</sup> = Constant (Preset) speed. Activation selects constant speed 1
16	DI 4	Digital input 4, programmable. Default <sup>2</sup> = Start enable 1 (safety interlock) Deactivation stops the drive.
17	DI 5	Digital input 5, programmable. Default <sup>2</sup> = Not configured.
18	DI 6	Digital input 5, programmable. Default <sup>2</sup> = Not configured.
19	RO1C	Common
20	RO1A	Normally Closed (NC)
21	RO1B	Normally Open (NO)
22	RO2C	Common
23	RO2A	Normally Closed (NC)
24	RO2B	Normally Open (NO)
25	RO3C	Common
26	RO3A	Normally Closed (NC)
27	RO3B	Normally Open (NO)
		Relay output 1, programmable (Default <sup>2</sup> = Ready - 19 connected to 21). 12 - 250 V AC / 30 V DC, 10 mA - 2 A
		Relay output 2, programmable (Default <sup>2</sup> = Running - 22 connected to 24). 12 - 250 V AC / 30 V DC, 10 mA - 2 A
		Relay output 3, programmable (Default <sup>2</sup> = Fault (-1) <sup>3</sup> - 25 connected to 27). 12 - 250 V AC / 30 V DC, 10 mA - 2 A
28	Screen	Terminal for signal cable screen. (Connected internally to chassis ground.)
29	B	RS-485 Serial Communications Positive input connection
30	A	RS-485 Serial Communications Negative input connection
31	AGND	Analog input common. (Connected internally to chassis ground through 1 M $\Omega$ .)
32	Screen	Terminal for signal cable screen. (Connected internally to chassis ground.)

- Notes:
1. Digital input impedance 1.5 k $\Omega$ . Maximum voltage for digital inputs is 30 V. Use multi-strand wire, size range: 20-16 AWG (0.5-1.5 mm<sup>2</sup>)
  2. Default values depend on the macro used. Values specified are for the HVAC default macro.
  3. For fail-safe reasons, the Fault (-1) Relay signals a "Fault", when the ACH550 is powered down.

# ACH550 with ABB E-Clipse bypass – Overview

## ***ABB E-Clipse bypass Standard Features***

- Door Interlocked Disconnect or Circuit Breaker
- English Language Back-Lit LCD Display
- Operator Control Panel
- LED Status Pilot Lights
- Smoke Control
- Override Mode
- Serial Communications
- 5 Programmable Relay Outputs (Form C)
- 100% Functionality with Drive Removed
- Programmable Auto Transfer to Bypass
- Plain English Safety Annunciation
- UL & cUL Listed
- Seismic Zone 4 Certified (IBC 2006)
- UL Type 1, Type 12 or Type 3R Enclosure
- Programmable Class 10, 20, or 30 OL
- Automatic Restart
- 24 Month Parts and Labor Warranty (with Certified Start-up)
- Two Contactor Bypass
- System Status Display
- Bypass Diagnostics Display
- Drive Exclusive Fast-Acting Fuses
- Electronic Motor Overload Protection
- Damper Control - VFD and Bypass Modes
- 6 Digital Inputs (5 programmable)
- Single Phase Protection in VFD & Bypass Mode
- Bullet Proof Contactor Protection
- Serial Communications Pass Through I/O
- Proof-of-Flow Indication & Action
- Conformal Coated Circuit Boards
- +30%; -35% Input Voltage Tolerance
- Run Permissive Circuit
- Supervisory Control
- UL Listed I<sup>2</sup>T Electronic Overload
- UL Listed and tested 100,000 Ampere SCCR (VCR and BCR Units)

The ACH550 with ABB E-Clipse bypass is an ACH550 HVAC Drive in an integrated UL Type 1, UL Type 12 or NEMA 3R enclosure with a bypass motor starter. The ACH550 with ABB E-Clipse bypass provides an input disconnect switch or circuit breaker with door mounted and interlocked operator (padlockable in the OFF position), a bypass starter, electronic motor overload protection, a local programming and operator keypad with indicating lights, provisions for external control connections, and serial communications capability. Certain configurations (+F267) also provide a drive service switch.

UL Type 1 (NEMA 1) and UL Type 12 (NEMA 12) E-Clipse units are available from 1 to 100 HP at 208/240V, 1 to 400 HP at 480V, and 2 to 150 HP at 600V. UL Type 1 and UL Type 12 units are wall mounted from 1 to 200 HP and floor mounted from 250 to 550 HP. The operator keypad is mounted on the door of the enclosure.

For outdoor applications, UL Type 3R (NEMA 3R) E-Clipse unit are available from 1 to 100 HP at 208/240V, 1 to 200 HP at 480V and 2 to 150 HP at 600V. Construction is sheet steel with a tough powder coat paint finish for corrosion resistance. A thermostatically controlled space heater and thermostatic control of the force ventilated cooling system are standard. The operator keypads are mounted on the enclosure door and covered by a hinged panel.

The ACH550 with ABB E-Clipse bypass includes two contactors. One contactor is the bypass contactor, used to connect the motor directly to the incoming power line in the event that the ACH550 is out of service. The other contactor is the ACH550 output contactor that disconnects the ACH550 from the motor when the motor is operating in the Bypass mode. The drive output contactor and the bypass contactor are electrically interlocked to prevent “back feeding”.



The ACH550 with ABB E-Clipse bypass is a microprocessor-controlled “intelligent” system which features programmable Class 20 or 30 overload curves, programmable underload (broken belt) and overload trip or indication. Also included as standard features are single-phase protection in bypass mode, programmable manual or automatic transfer to bypass, fireman’s override, smoke control, damper control, no contactor chatter on brown-out power conditions and serial communications. Should a drive problem occur, fast acting fuses exclusive to the ACH550 drive path disconnect the drive from the line prior to clearing upstream branch circuit protection, maintaining bypass capability.

## **Damper Control Circuit (Run Permissive)**

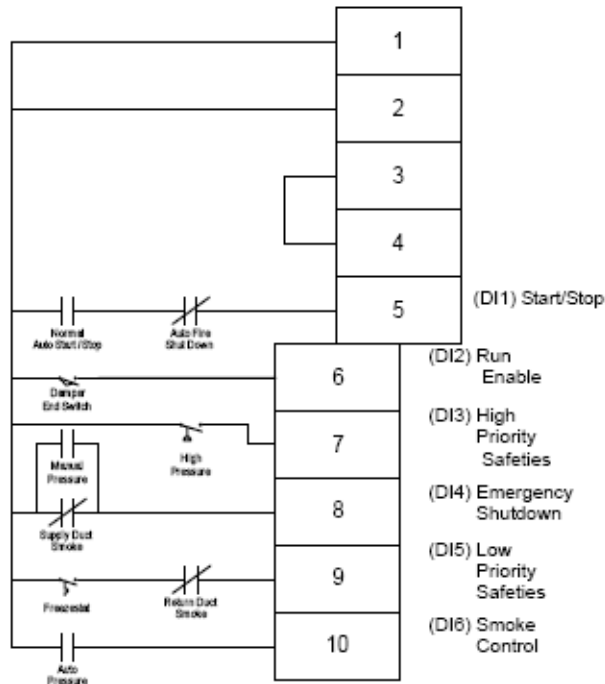
The damper control circuit closes a dry contact upon a start command to open a damper such as an outdoor air damper, fire damper, isolation damper, etc. before the motor is allowed to operate in drive mode or bypass mode regardless of the source of the run command. When the damper is fully open, a normally open dry contact from the damper end-switch closes and allows the motor to operate. Up to four dedicated inputs are provided for safety interlocks such as firestats, smoke detectors, etc.

The safety interlock inputs may also be linked to plain English keypad diagnostic indications to be displayed on the LCD. The unit may be set-up to display any of the following diagnostics upon opening of a digital input: Vibration Switch; Firestat; Freezestat; Over Pressure; Vibration Trip; Smoke Alarm; Safety Open; Low Suction; Start Enable; Run Enable; Damper End Switch; Valve Open Proof; or Pre-Lube Cycle. When any of these contacts open, the motor stops (in drive or bypass mode) and the damper is commanded to close. Although it is not a recommend sequence of operation, this run permissive circuit may also be controlled via serial communications.

## **Smoke Control and Override Modes**

The ACH550 with ABB E-Clipse bypass has two Override modes of operation for critical control situations. The Smoke Control Override accepts a normally open dry contact that forces the motor to run in bypass and ignores all keypad inputs. In Smoke Control Override mode, the system acknowledges high priority digital inputs such as overpressure safeties and damper end-switch run permissive proofs, and disregards other, low priority digital inputs. See the attached sample wiring diagram for further details. Smoke Control Override (Override 1) response is not field programmable. The unit will go into smoke Override mode whenever DI6 is closed.

### X2 E-Clipse Bypass Controller Input



#### Normal Operation:

- Close Start/Stop (X2:5)
- Fan starts, assuming that X2: 6, 7, 8, and 9 are all closed

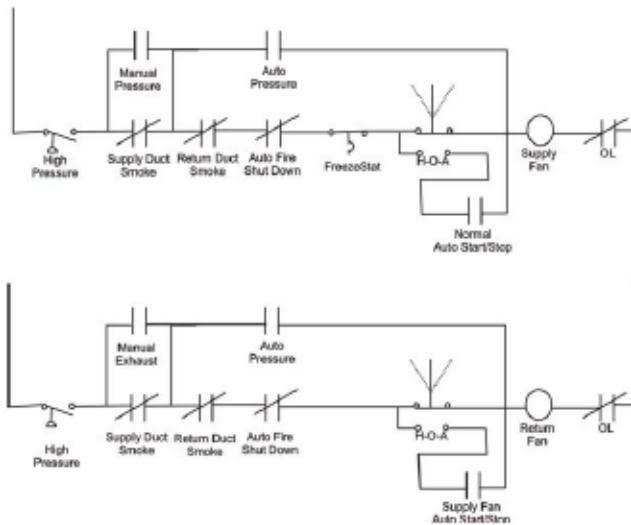
#### Emergency Shutdown:

- Open auto fire shutdown, unit stops

#### Smoke Control Mode:

- Close contact on X2:10
- Fan starts regardless of position of internal HOA switch and inputs X2:6 and X2:9
- Inputs X2:6, 7 and 8 followed
- Internal overloads followed

### Typical Starter Wiring for a Smoke Control listed System Today:



#### Notes:

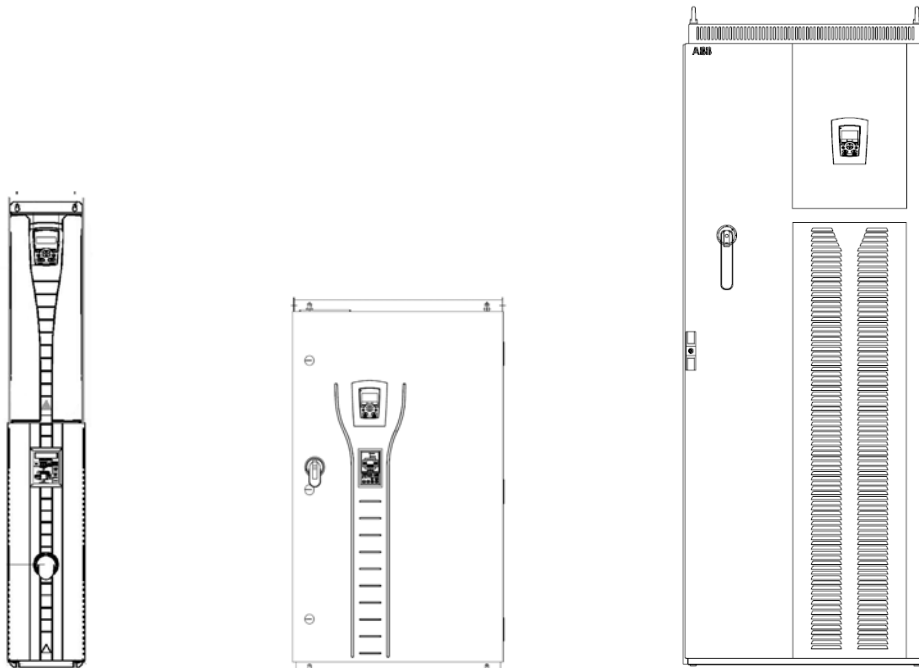
1. Pressure cutouts, duct smoke detectors and auto shutdown are 2-pole.
2. Manual control also activates "auto control" relays.

The second mode, Override 2, is fully programmable. Override 2 default programming is designed for “Run to Destruction” operation. However, the end user can program the unit to acknowledge some external inputs while ignoring others, ignore all external inputs or acknowledge all external inputs. This mode is fully programmable to allow the user to program the response of the unit to match his local AHJ.

## Serial communications

All ABB E-Clipse bypass units have the following Embedded Fieldbus (EFB) protocols included as standard: Modbus RTU; Johnson Controls N2; Siemens Building Technologies FLN (P1); and BACnet (MS/TP).

The ACH550 with ABB E-Clipse bypass has the ability to monitor VFD/Bypass mode of operation, the status of the bypass H-O-A switch, bypass fault and override status over serial communication. In addition, the user can monitor and / or control over 45 points of bypass information via the communications protocols. Serial communication capabilities include - bypass run-stop control; the ability to force the unit to bypass; and the ability to control all relay outputs. The DDC system can monitor bypass feedback such as, current (in amps), kilowatt hours (resettable), operating hours (resettable), and bypass logic board temperature. The DDC system is also capable of monitoring the bypass relay output status, and all digital input status'. All bypass diagnostic warning and fault information is transmitted over the serial communications bus. Remote system (drive or bypass) fault reset is possible.



Vertical & Standard ABB E-Clipse bypass Exterior Views

# ABB E-Clipse bypass Operator Control

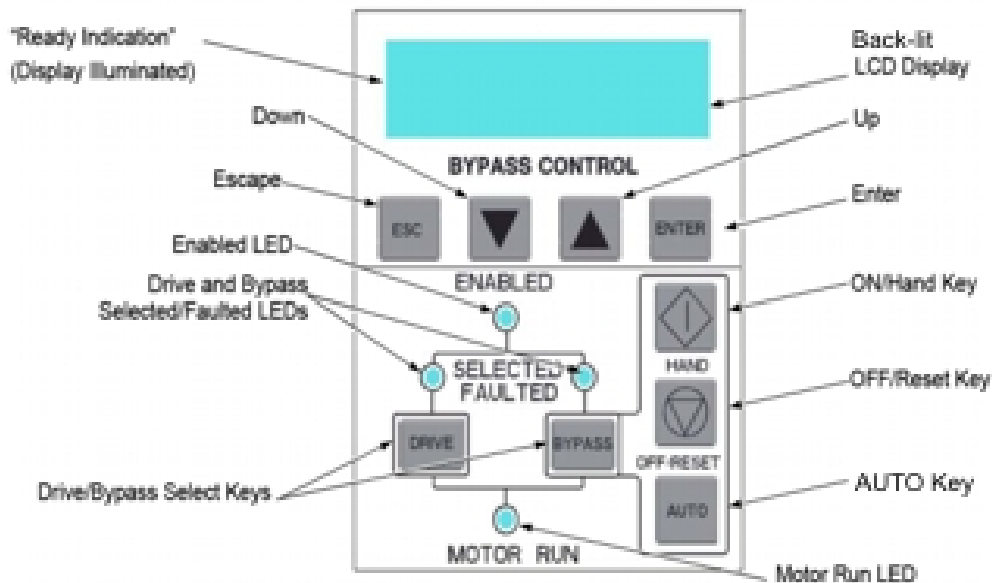
## ACH550 Control Panel

The ACH550 Control Panel is a keypad with an LCD unit that provides status indication and operator controls for the ACH550 drive. In normal operation with the ABB E-Clipse bypass, the ACH550 should be placed in the *Auto* mode of operation by pressing the *Auto* key on the ACH550 Control Panel. Refer to the *ACH550 User's Manual* for additional information on the ACH550 Control Panel and other aspects of ACH550 operation.

## Bypass Control Keypad

The ABB E-Clipse bypass has a separate keypad with an LCD unit that provides status indication and programming of the system. This keypad is also used for selecting the *Drive* or *Bypass* mode of operation and manually starting and stopping the motor in the *Bypass* mode. The bypass keypad has LED indicating lights that indicate the status of both the bypass and the drive as well as an LCD display that provides programming, status and warning/fault indications.

The illustration below shows the bypass control keypad and identifies the keys and LED indicating lights.



The functions of the various keys and LEDs are described in the following table.

<b>Enabled LED</b>	<p>The <i>Enabled</i> LED is illuminated green under the following conditions:</p> <ul style="list-style-type: none"> <li>• Both the Safety Interlock(s) and Run Enable contacts are closed.</li> <li>• The Safety Interlock(s) contact are closed with no Start command present.</li> </ul> <p>The <i>Enable</i> LED flashes green if the Run Enable contact is open and when the Safety Interlock contact(s) are closed and a Start command is present.</p> <p>The Enable LED is illuminated red when the Safety Interlock contact(s) are open.</p>
<b>Drive Selected LED</b>	The <i>Drive Selected</i> LED is illuminated green when the drive has been selected as the power source for the motor and no drive fault is present.
<b>Bypass Selected LED</b>	The <i>Bypass Selected</i> LED is illuminated green when the bypass has been selected as the power source for the motor and no bypass fault is present.
<b>Motor Run LED</b>	The <i>Motor Run</i> LED is illuminated green whenever the system is running. The <i>Motor Run</i> LED flashes green to indicate the system has been placed in an Override operating mode.
<b>Drive Faulted LED</b>	The <i>Drive Fault</i> LED is illuminated red when the bypass has lost its' communications link with the drive or when the motor or drive protection functions have shut down the drive.
<b>Bypass Faulted LED</b>	The <i>Bypass Faulted</i> LED is illuminated or flashes red when the motor or bypass protective functions have shut down the bypass.
<b>Drive Key</b>	The <i>Drive Key</i> selects the drive as the power source for the motor.
<b>Bypass Key</b>	The <i>Bypass Key</i> selects the bypass as the power source for the motor.
<b>Auto Key</b>	The <i>Auto</i> key selects the <i>Auto Start</i> contact or serial communications as the means for starting and stopping the motor in the bypass mode.
<b>Off/Reset Key</b>	The <i>Off/Reset</i> key may be used to manually stop the motor if the motor is running on bypass power. The <i>Off/Reset</i> Key also resets most bypass faults. It may take several minutes before the bypass can be reset after an overload trip. If a bypass fault condition is present, the second push of the <i>Off/Reset</i> key puts the bypass in the Off mode.
<b>Hand Key</b>	The <i>Hand</i> key can be used to manually start the motor when the bypass has been selected as the power source for the motor.
<b>UP Key</b>	Used to navigate through system programming steps.
<b>Down Key</b>	Used to navigate through system programming steps.

## Control Modes

### Drive mode

Under normal conditions the system is in the *Drive* mode. The ACH550 drive provides power to the motor and controls its speed. The source of the drive's start/stop and speed commands is determined by the *Auto* or *Hand* mode selection of the drive's keypad. Commands come from the control terminals or serial communications when the *Auto* mode has been selected or from the drive keypad when the *Hand* mode has been selected. The user can normally switch to the *Drive* mode by pressing the *Drive* key on the bypass keypad.

### Bypass mode

In the *Bypass* mode, the motor is powered by AC line power through the bypass contactor. The source of the bypass's start/stop commands is determined by the *Auto* or *Hand* mode selection of the bypass' keypad. Commands come from the control terminals or serial communications when the *Auto* mode has been selected or from the bypass keypad when the *Hand* mode has been selected. The user can normally switch to the *Bypass* mode by pressing the *Bypass* key on the bypass keypad.

### Smoke Control mode

In the *Smoke Control (Override 1)* mode, the motor is powered by AC line power through the bypass contactor. The source of the Smoke Control command is DI 6 and is unaffected by external stop commands. The VFD Keypad and the Bypass Keypad will not accept user commands when the system is in Smoke Control mode (the keypad user inputs are disabled). The user can switch to the *Smoke Control* mode by closing the *Smoke Control* input contact (DI 6). When the *Smoke Control* input contact is closed, the system is forced to bypass and runs the motor. The Motor Run LED flashes green when the system is in override. While in *Smoke Control*, the system only responds to certain inputs. Normally when the *Smoke Control* input contact is switched from closed to open, the system returns to the operating mode that existed prior to entering *Smoke Control* and can once again be controlled using the *Drive* and *Bypass* keys. The exception to this is when the *Bypass Override (Override 2)* input contact is closed, in which case the system switches to *Bypass Override* operation.

### Bypass Override mode

In the *Bypass Override (Override 2)* mode, the motor is powered by AC line power through the bypass contactor. The source of the start command is internal and unaffected by external stop commands. The VFD Keypad and the Bypass Keypad will not accept user commands when the system is in Bypass Override mode (the keypad user inputs are disabled). The user can switch to the *Bypass Override* mode by closing the *Bypass Override* input contact (DI 5-if programmed). When the *Bypass Override* input contact is closed, the system is forced to bypass and does not respond to the *Drive* and *Bypass* keys. The Motor Run LED flashes green when the system is in override. While in *Bypass Override* the system responds to bypass overloads and programmed faults. The system may be custom programmed to acknowledge or disregard certain faults, safeties and enables. The unit is default programmed to ignore all external safeties and run enables. See Group 17 for programmability of the digital input and fault functions. Normally when the *Bypass Override* input contact is switched from closed to open, the system switches to the *Drive* mode and can be controlled using the *Drive* and *Bypass* keys. The exception to this is when the *Smoke Control (Override 1)* input contact is closed, in which case the system remains in *Smoke Control* operation.

### Hand mode

When the system is in the *Bypass* mode, the operator can manually start the motor by pressing the *Hand* key. The motor will run and the *Hand* LED will be illuminated green. In order to run the motor, the *Safety Interlock* and *Run Enable* contacts must be closed (green *Enable* LED) and any bypass fault must be reset.

### Auto mode

In the *Auto* mode the bypass start/stop command comes from the *Start/Stop* input terminal on the bypass control board or from serial communications – if programmed. The *Auto* mode is selected by pressing the

*Auto* key on the bypass keypad. The *Auto* LED is illuminated green when the bypass is in the *Auto* mode. If the system is in the *Bypass* mode, the motor will run across the line if the *Auto* mode is selected, the *Start/Stop*, *Safety Interlock* and *Run Enable* contacts are closed and any bypass fault is reset.

## **Off Mode**

If the motor is running in the *Bypass* mode, the operator can manually stop the motor by pressing the *OFF* key. The *Motor Running* LED will go out. The motor can be restarted by pressing the *Hand* key or the bypass can be returned to the *Auto* mode by pressing the *Auto* key. If the system is in the *Drive* mode, pressing the *OFF* key will take the bypass out of the *Auto* mode, but will not affect motor operation from the drive. If the system is switched to the *Bypass* mode, a motor that is running will stop.

## **Programmable Relay Contact Outputs**

The ABB E-Clipse bypass has five programmable relay outputs as standard. The default programming descriptions for these relay outputs is described below.

### **Bypass Not Faulted**

The *Bypass Not Faulted* relay is energized during normal operation. The *Bypass Not Faulted* relay is de-energized when a bypass fault has occurred.

### **System Running**

The *System Running* relay is energized when the ABB E-Clipse bypass System is running. The *System Running* relay provides an output when the motor is running whether powered by the ACH550 drive or the bypass.

### **System Started**

The *System Started* relay is energized when the ABB E-Clipse bypass system is started. Three conditions must be met in order for the relay to energize. 1) a *Start* command must be present, 2) the *Safety Interlock* input contact must be closed and 3) there can be no fault present in the system. The *Start* command can come from the bypass control board terminal block, the ACH550 keypad, the bypass keypad, or serial communications depending on the operational mode selected. The *System Started* relay is ideal for use in damper actuator circuits, opening the dampers only under those conditions where the system is preparing to run the motor. The *System Started* relay will de-energize, closing the dampers if the safeties open, the system faults, or when a *Stop* command is issued.

## Bypass Selected

Relay output four is factory default programmed for Bypass Selected. The relay will be energized anytime the user has placed the system in Bypass mode.

## Bypass Auto

Relay Output five is factory default programmed for *Bypass Auto*. The relay will be energized anytime the user has placed the bypass in the Auto mode.

The complete list of programmable relay output functions follows:

0 = NOT SEL	10 = DRV NOT FLT	20 = BYP UNDERLD
1 = SYS READY	11 = DRIVE ALARM	21 = PCB OVERTMP
2 = SYS RUNNING	12 = OVERRIDE	22 = SYS UNDERLD
3 = SYS STARTED	13 = BYPASS HAND	23 = SYSTEM FLT
4 = BYPASS SEL	14 = BYPASS OFF	24 = SYS FLT/ALM
5 = BYPASS RUN	15 = BYPASS AUTO	25 = SYS EXT CTL
6 = BYPASS FLT	16 = COM CTRL	26 = SYS OVERLD
7 = BYP NOT FLT	17 = SYS ALARM	27 = CONTACT FLT
8 = BYPASS ALRM	18 = BYPASS FLT/ALM	
9 = DRIVE FAULT	19 = BYP OVERLD	

## Cable Connections

The following illustrations show the ACH550 with ABB E-Clipse bypass cable connection points for the various enclosure styles. The illustrations indicate the location of input and output power connections as well as equipment and motor grounding connection points.

ACH550 drives are configured for wiring access from the bottom only on Vertical ABB E-Clipse bypass units and from the top only on Standard ABB E-Clipse bypass units. At least three separate metallic conduits are required, one for input power, one for output power to the motor and one for control signals.

All ABB E-Clipse bypass units provided with a circuit breaker input - VCR and BCR configurations have a panel short circuit current rating of 100,000 RMS symmetrical Amperes. Units provided with a disconnect input - VDR and BDR configurations require separate external low peak fuses (supplied by others) to obtain the 100,000 KAIC SCCR.

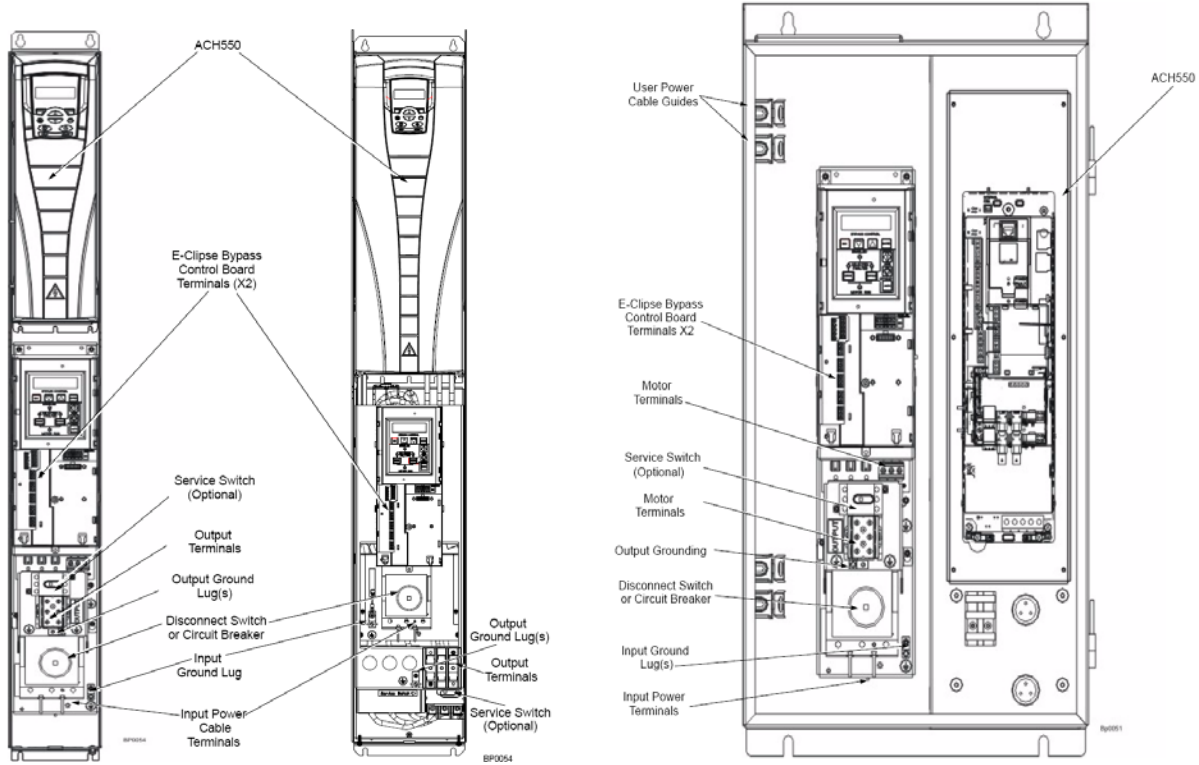
## Terminal Sizes

Power and motor cable terminal sizes are shown in the *Submittal Schedule Details* and in the *Wire Size Capacities of Power Terminals* Table. The information provided is for connections to an input circuit breaker or disconnect switch, a motor terminal block, overload relay and ground lugs. The table also lists torque that should be applied when tightening the connections.

## Protections

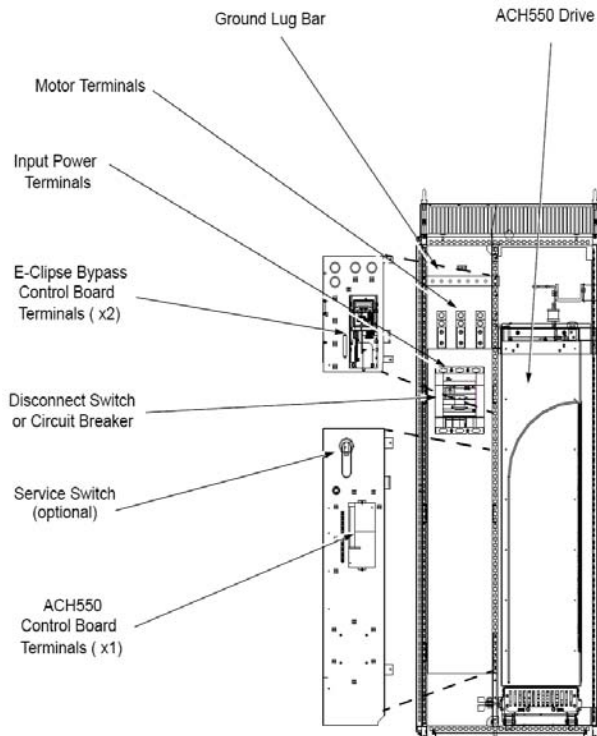
All ABB E-Clipse bypass units include the following protective features: single phase input and output; motor open phase; motor overload (UL Listed); stuck contactor; contactor coil open; undervoltage; motor underload (proof-of-flow / broken belt); serial communications loss; and overtemperature. All printed circuit boards are conformally coated as standard.

# Internal Layout Drawings



Vertical ABB E-Clipse Bypass  
(UL Type 1 / 12)

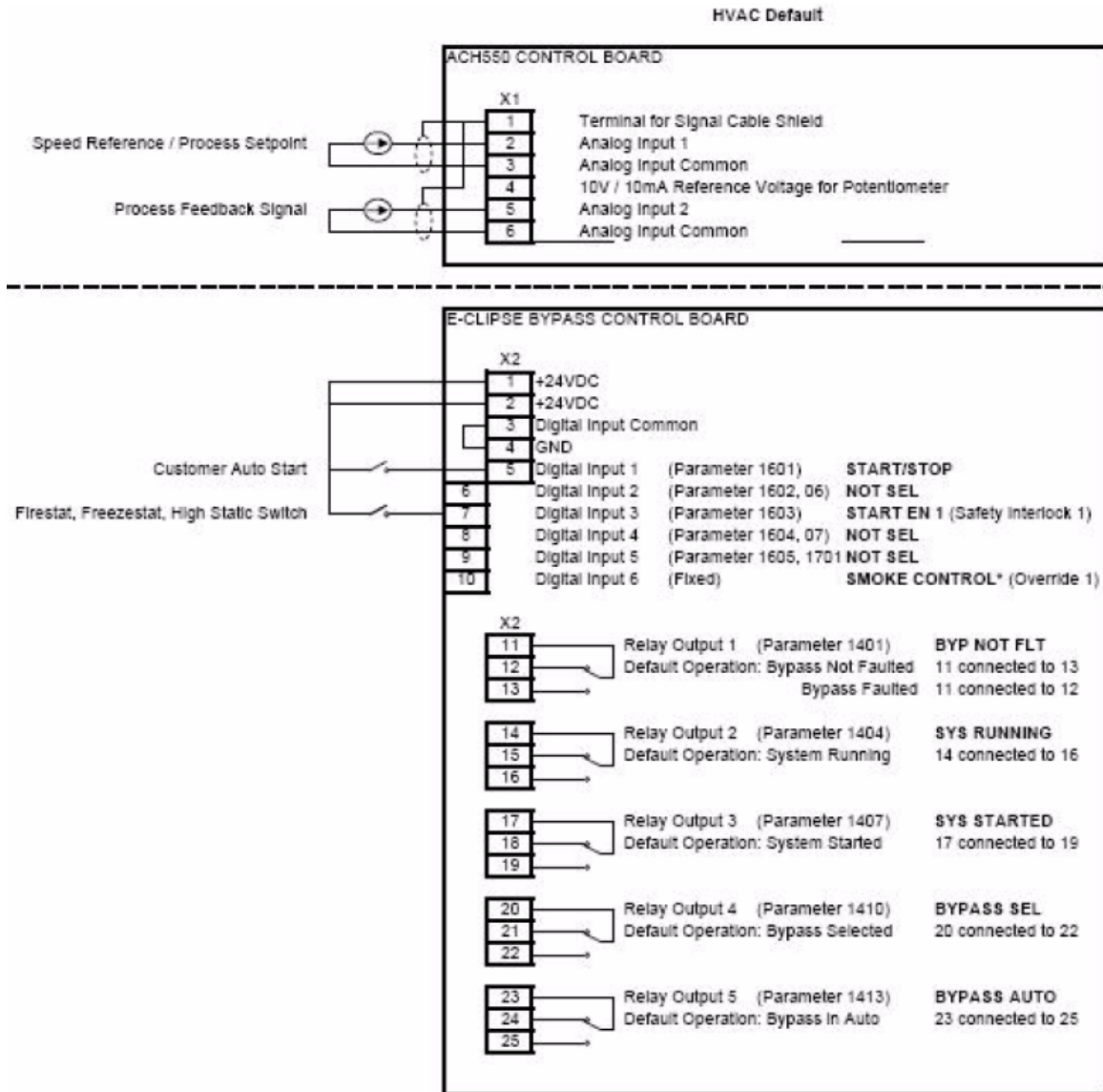
Standard Wall Mount ABB E-Clipse Bypass



Standard Floor Mount ABB E-Clipse Bypass

## Control Terminals

The control wiring includes connections to an analog speed command signal and a start/stop relay contact for controlling the motor in the AUTO mode. There may also be connections to external run enable interlock contacts and a connection from the Motor Run contact to an external status indication circuit. For a detailed description of the control circuit functions and alternate Control Connection diagrams, refer to the *ACH550 with ABB E-Clipse bypass Users Manual*.



Basic Control Connections for Damper Actuator Control

# Engineering Data and Ratings Tables

## Fuses

Drive input fuses are recommended to disconnect the drive from power in the event that a component fails in the drive's power circuitry. Recommended drive input fuse specifications are listed in the *Submittal Schedule Details* and in the *Fuse Ratings Table*. Fuse rating information is provided for customer reference.

Item	Catalog Number	Drive Input Fuse Ratings	
		Amps (600V)	Bussmann Type
1	ACH550-BCR-157A-4+B055	200	170M1370 or M2617
2	ACH550-BCR-125A-4+B055	200	170M1370 or M2617
3	ACH550-BCR-031A-4+B055	60	JJS-60
4	ACH550-BCR-078A-4+B055	100	JJS-100

## Terminal Sizes / Cable Connection Requirements

Power and motor cable terminal sizes and connection requirements are shown in the *Submittal Schedule Details* and in the *Terminal Sizes / Cable Connection Requirements Table*. The information provided below is for connections to input power and motor cables. These connections may be made to an input circuit breaker or disconnect switch, a motor terminal block, overload relay, and/or directly to bus bars and ground lugs. The table also lists torque that should be applied when tightening terminals and spacing requirements where multiple mounting holes are provided in the bus bar.

Item	Catalog Number	Circuit Breaker	Disconnect Switch	Terminal Block	Overload Relay	Ground Lug
1	ACH550-BCR-157A-4+B055	350MCM 274 in-lbs	N/A N/A	250 MCM 300 in-lbs	N/A N/A	3 x #3/0 250 in-lbs
2	ACH550-BCR-125A-4+B055	350MCM 274 in-lbs	N/A N/A	250 MCM 300 in-lbs	N/A N/A	3 x #3/0 250 in-lbs
3	ACH550-BCR-031A-4+B055	#1 50 in-lbs	N/A N/A	#2 50 in-lbs	N/A N/A	#2 50 in-lbs
4	ACH550-BCR-078A-4+B055	#1 50 in-lbs	N/A N/A	#2/0 120 in-lbs	N/A N/A	#2 50 in-lbs

## Heat Dissipation Requirements

The cooling air entering the drive must be clean and free from corrosive materials. The *Submittal Schedule Details* and the *Heat Dissipation Requirements table* below give the heat dissipated into the hot air exhausted from the drives. If the drives are installed in a confined space, the heat must be removed from the area by ventilation or air conditioning equipment.

Item	Catalog Number	Power Losses		Airflow	
		Watts	BTU/Hr	CFM	CM/Hr
1	ACH550-BCR-157A-4+B055	2310	7884	238	405
2	ACH550-BCR-125A-4+B055	1940	6621	99	168
3	ACH550-BCR-031A-4+B055	457	1560	79	134
4	ACH550-BCR-078A-4+B055	1295	4420	165	280

## Dimensions and Weights

Dimensions and weights of the drives provided are given in the *Submittal Schedule Details* and in the *Dimensions and Weights* Table. The table also lists the applicable dimension drawings that include additional detail. Dimension drawings may be provided in the back of this submittal.

Item	Catalog Number	Height mm / in	Width mm / in	Depth mm / in	Weight kg / lbs	Dimension Drawing
1	ACH550-BCR-157A-4+B055	1380 / 54.3	713 / 28.1	483 / 19	163 / 360	3AUA0000016382 Sheet 1
2	ACH550-BCR-125A-4+B055	1380 / 54.3	713 / 28.1	483 / 19	121 / 266	3AUA0000016382 Sheet 1
3	ACH550-BCR-031A-4+B055	950 / 37.4	521 / 20.5	389 / 15.3	54.4 / 120	3AUA0000016379 Sheet 1
4	ACH550-BCR-078A-4+B055	950 / 37.4	521 / 20.5	389 / 15.3	62.6 / 138	3AUA0000016379 Sheet 1

## Schematics and Wire Diagrams

Detailed wiring diagrams and schematics may be included for the products covered in this submittal. Please reference the following ABB part numbers for the drawings included with this submittal:

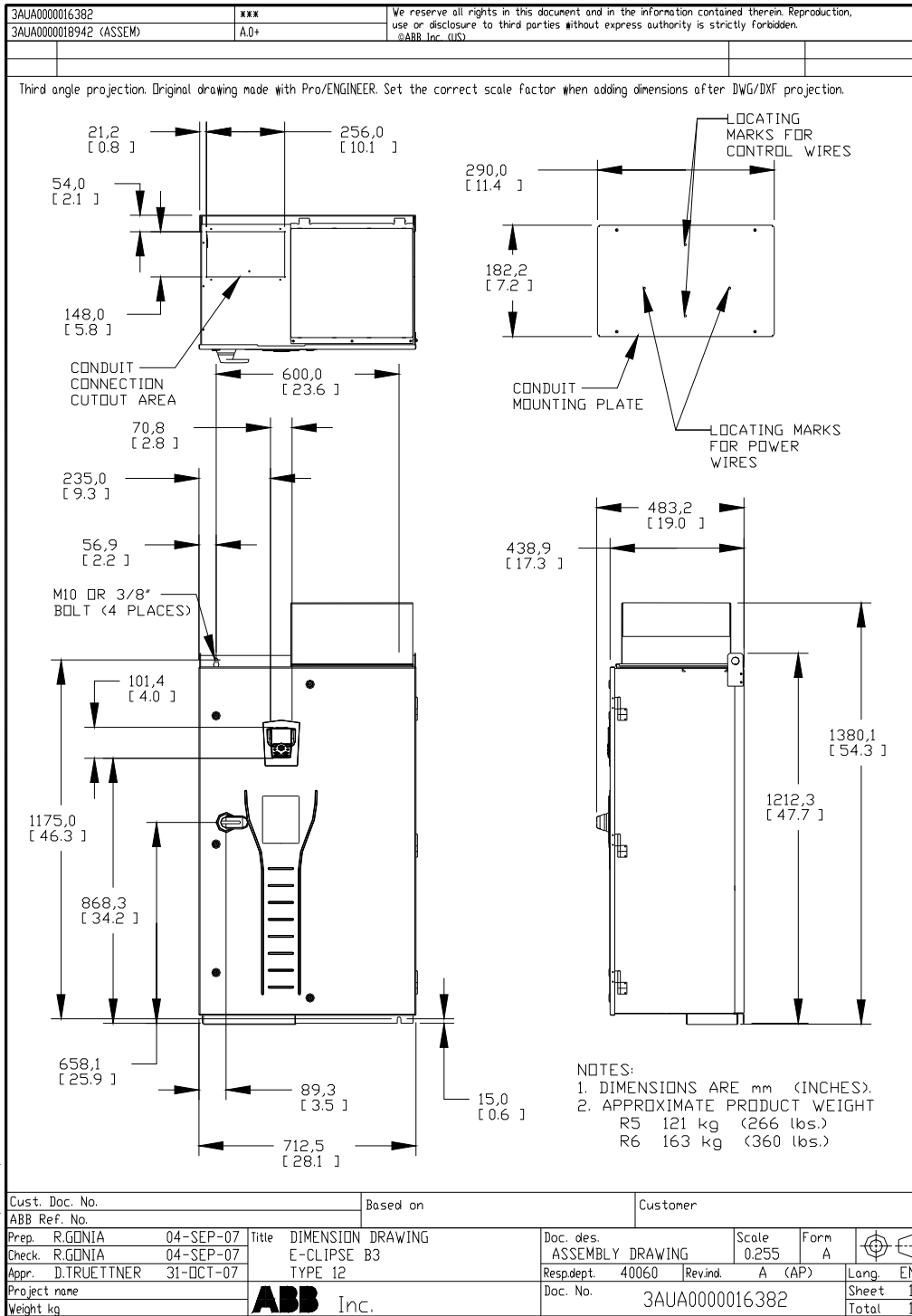
Item	Catalog Number	Power Wiring	Connection Diagram	Dimension Detail
1	ACH550-BCR-157A-4+B055	BC00R046PW-A	BCBDR016CC-A	3AUA0000016382 Sheet 1
2	ACH550-BCR-125A-4+B055	BC00R046PW-A	BCBDR016CC-A	3AUA0000016382 Sheet 1
3	ACH550-BCR-031A-4+B055	BC00R024PW-A	BCBDR016CC-A	3AUA0000016379 Sheet 1
4	ACH550-BCR-078A-4+B055	BC00R024PW-A	BCBDR016CC-A	3AUA0000016379 Sheet 1

## Product short Circuit Current Rating

Short circuit ratings shown below are as show on the device rating label.

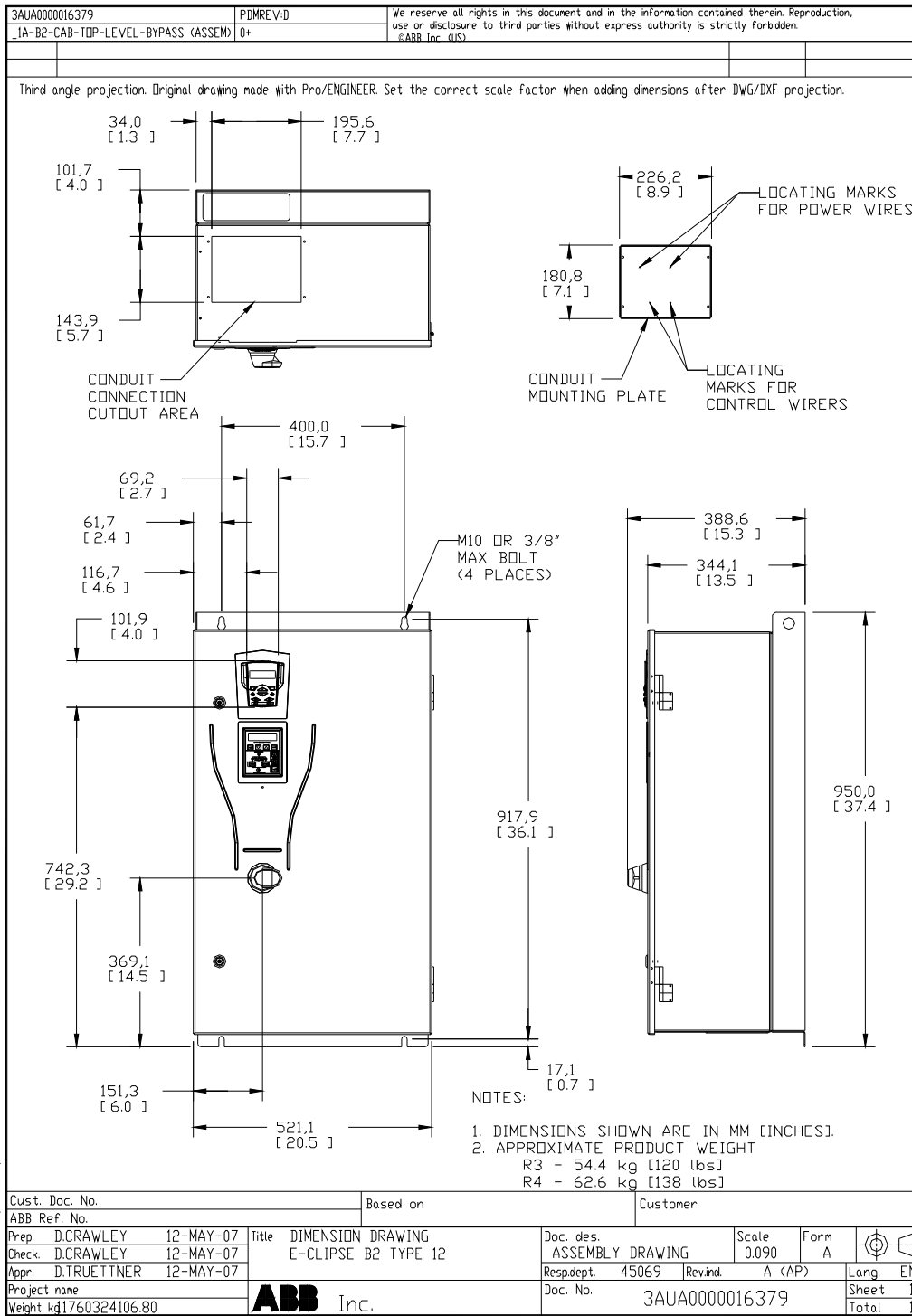
Item	Catalog Number	Short Circuit Current Rating
1	ACH550-BCR-157A-4+B055	100 kA
2	ACH550-BCR-125A-4+B055	100 kA
3	ACH550-BCR-031A-4+B055	100 kA
4	ACH550-BCR-078A-4+B055	100 kA

# Dimension Drawing for CHWP-11,12, CWP-13,14



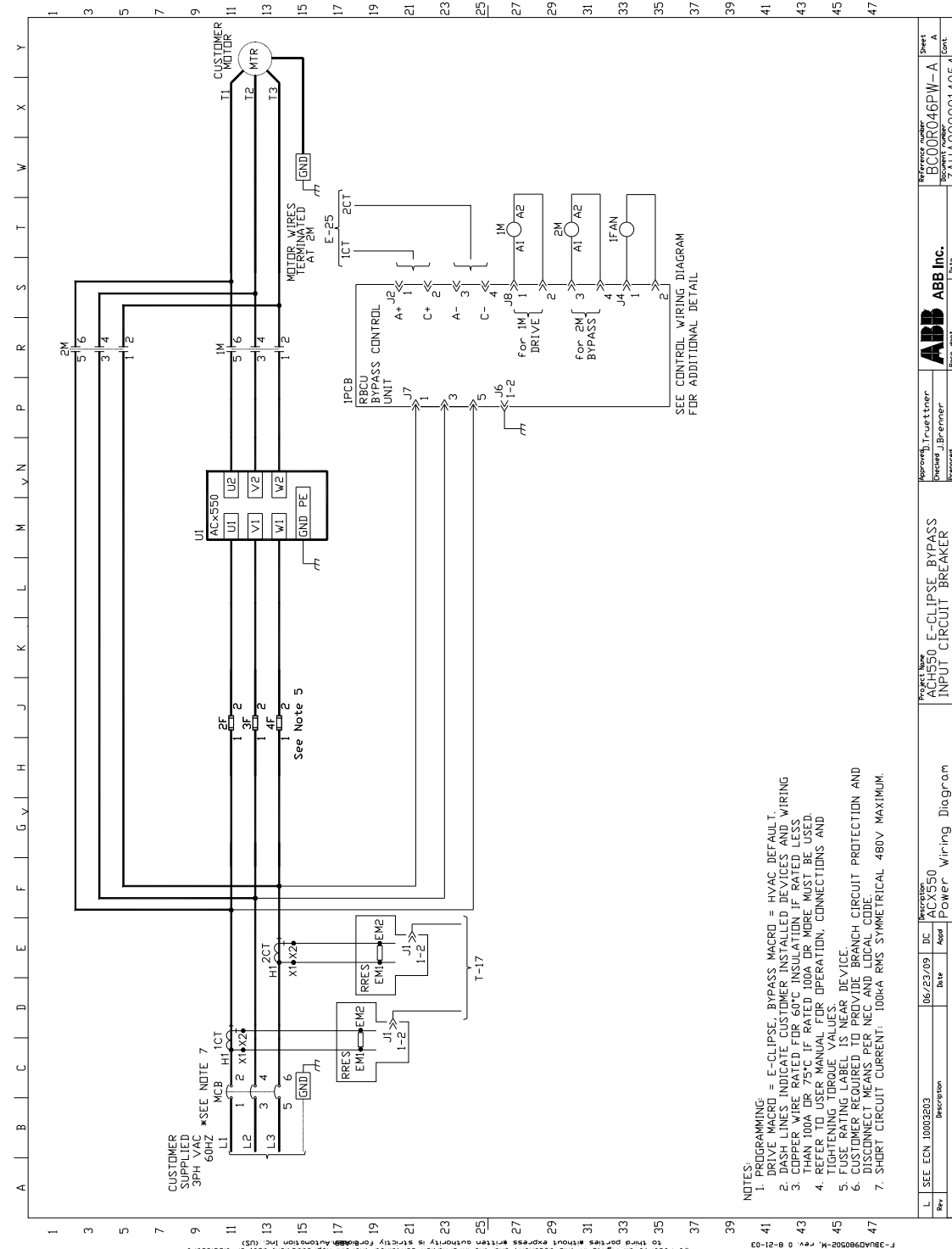
F-3BUA0981052-k, rev. 2, 10-21-04

# Dimension Drawing for ICWP-17,18, PWP-3,4, CT-4,5





# Power Drawing for CHWP-11,12, CWP-13,14



- NOTES:
1. PROGRAMMING: DRIVE MACRO = E-CLIPSE, BYPASS MACRO = HVAC DEFAULT.
  2. DASH LINES INDICATE CUSTOMER INSTALLED DEVICES AND WIRING.
  3. DRIVE WIRE GAUGE AND CONDUIT SIZE MUST BE USED.
  4. REFER TO USER MANUAL FOR OPERATION, CONNECTIONS AND TIGHTENING TORQUE VALUES.
  5. FUSE RATING LABEL IS NEAR DEVICE.
  6. CUSTOMER REQUIRED TO PROVIDE BRANCH PROTECTION AND DISCONNECT MEANS PER NEC AND LOCAL CODE.
  7. SHORT CIRCUIT CURRENT: 100kA RMS SYMMETRICAL 480V MAXIMUM.

Rev	Description	Date	App'd	Microchip	DC	Project Name	Approved By	Reference Number	Sheet
L	SEE ECN 10002803	06/23/09		DC	ACX550	E-CLIPSE BYPASS INPUT CIRCUIT BREAKER	J. Truetzner	BC00R046PW-A	1 of 2
							J. Brenner		A
							Sch Gen		B
							Res	3AU0000014954	

